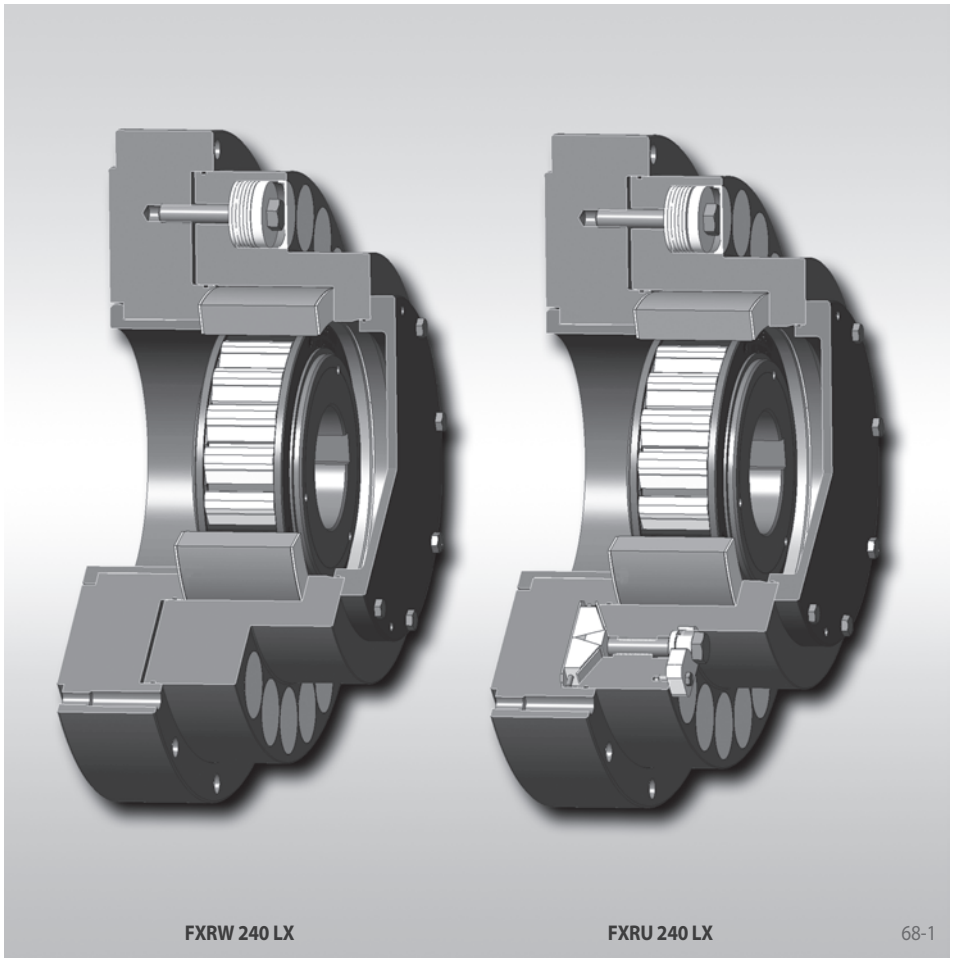
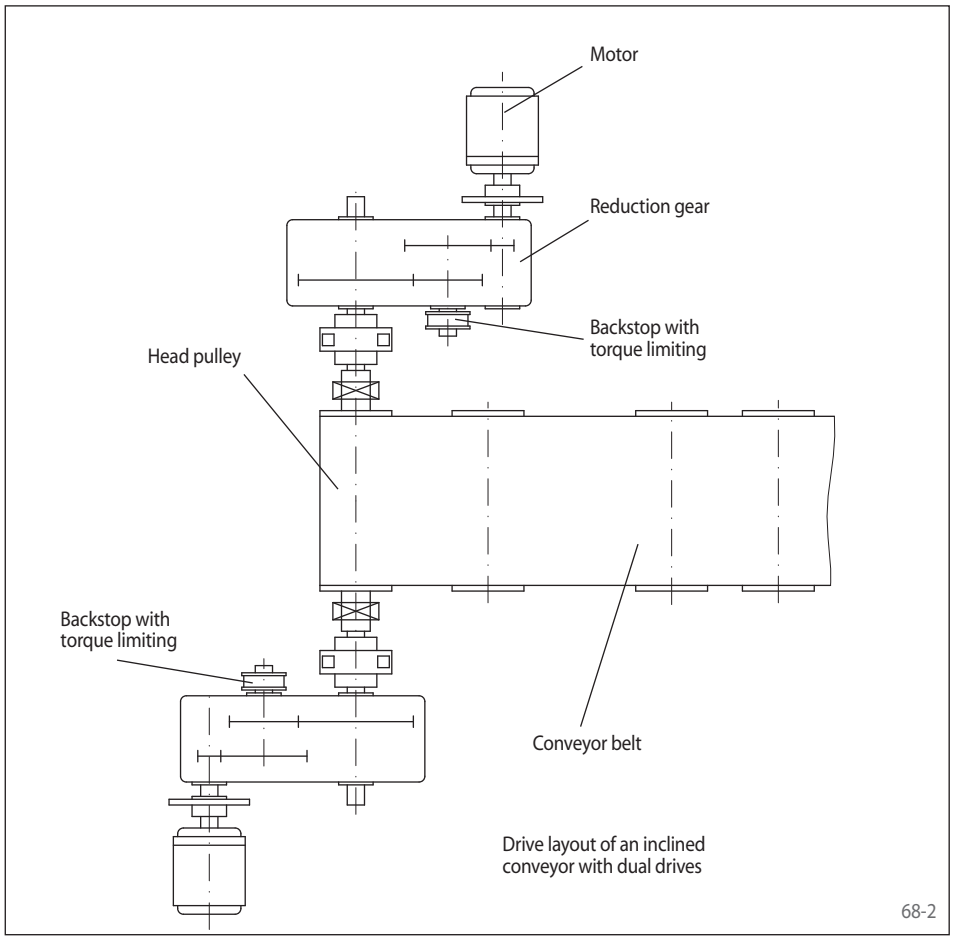
Integrated Freewheels FXR …

for bolting to the face with sprag lift-off X and torque limiting

RINGSPANN®



FXRW 240 LX FXRU 240 LX 68-1



Drive layout of an inclined conveyor with dual drives

68-2

Application as

- Backstop

for continuous conveyor installations with multiple drives in which each drive is equipped with a backstop.

Features

Integrated Freewheels FXR … are sprag freewheels without bearing support and with sprag lift-off X. They consist of the Integrated Freewheels FXM (refer to pages 60 to 65) with additional torque limiter.

The sprag lift-off X ensures a wear-free freewheeling operation when the inner ring rotates at high speed.

In continuous conveyor installations with multiple drives it is important to consider the problem of the unequal distribution of backdriving torque to the individual drives and backstops. As soon as the installation comes to a standstill, the entire backdriving torque is applied primarily to a single backstop, due to differences in the play and elasticity of the drives involved. In installations equipped with backstops without torque limiters, the individual gearboxes and the corresponding backstops must be designed to accommodate the entire backdriving torque of the conveyor installation in order to ensure safety.

The problem of the unequal distribution of backdriving torque is solved by using backstops FXR … with torque limiting. The torque limiter which is built into the backstop slips temporarily when the specified torque is exceeded until the other backstops engage in succession. In this way, the entire backdriving torque of the conveyor installation is distributed to the individual gearboxes and backstops. Furthermore, dynamic peak torques which occur during the locking process are reduced, thereby protecting the gearboxes against damaging peak torques. For this reason the use of backstops FXR … with torque limiting in continuous conveyor installations with multiple drives enables the application of gearboxes with smaller dimensions.

Advantages

- Protection of gearboxes from overload by unequal load distribution in multiple drives
- Protection of gearboxes from dynamic peak torques during the locking process
- Smaller gearboxes can be used without negatively effecting the safety
- Protection of the backstops, as dynamic peak torques are reduced by temporarily slipping

Integrated Freewheels FXRW and FXRV with torque limiting and without release function

This series of backstops with torque limiting is the basic version. The design and the available standard sizes are shown on page 70 and 72.

Integrated Freewheels FXRU and FXRT with torque limiting and with release function

This series is designed in the same way as series FXRW or FXRV; as an addition, a finely controllable release function is built in. The design, the description of the release function and the available standard sizes are shown on page 71 and 73.

The backstops with controllable release function are used if a controlled relaxing of the belt or the unit – perhaps in the case of a jam on the pulley drum – or a limited reverse movement of the conveyor system is required.

Selection torque

The following determination of the selection torque applies to multiple-drives installations in which each drive has the same motor power. Please contact us in case of different motor powers.

If the backdriving torque M_L per drive is known, then the selection torque M_A for the particular backstop should be determined as follows:

$M_A = 1{,}2 \cdot M_L$ [Nm]

If, however, only the nominal power per drive P_0 [kW] is known, then this applies:

$M_A = 1{,}2 \cdot 9550 \cdot F^2 \cdot P_0 / n_{SP}$ [Nm]

In these equiations:

M_A = Selection torque of the particular backstop [Nm]

M_L = $9550 \cdot F \cdot P_L / n_{SP}$ [Nm]

= Static backdriving torque of the load for each drive referring to the particular backstop shaft [Nm]

P_L = Lifting capacity per drive at full load [kW]

= Lifting height [m] multiplied by the load that is being conveyed per second divided by the number of drives [kN/s]

P_0 = Nominal power of motor [kW]

n_{SP} = Speed of backstop shaft [min^{-1}]

F = Selection factor

$$= \frac{\text{Lifting capacity}}{\text{Lifting capacity + Power loss}}$$

After calculating M_A, the size of the particular backstop must be selected in accordance with the catalogue tables in such a way that in all cases this applies:

$M_R \geqq M_A$

M_R = Maximum slipping torque of the particular backstop in accordance with the table values on pages 70 to 73 [Nm]

Approximate values for F:

Type of installation	F	F^2
Conveyor belts, angle up to 6°	0,71	0,50
Conveyor belts, angle up to 8°	0,78	0,61
Conveyor belts, angle up to 10°	0,83	0,69
Conveyor belts, angle up to 12°	0,86	0,74
Conveyor belts, angle up to 15°	0,89	0,79
Screw pumps	0,93	0,87
Ball mills, drying drums	0,85	0,72
Bucket conveyors, elevators	0,92	0,85
Hammer mills	0,93	0,87

In each case, the sum of the slipping torques of the particular backstops must be 1,2 times higher than the static backdriving torque of the installation (also at overload). The torques specified in the tables are maximum values. Lower values can be set upon request. If in doubt, please contact us stating the precise description of the installation and the operating conditions. It is preferable to use the questionnaire on page 112.

Example

Dual-drive system

Motor power per drive: $P_0 = 630$ kW

Type of installation:

Conveyor belt with 8° incline => $F^2 = 0{,}61$

Speed per backstop shaft:

n_{SP} = 360 min^{-1}

Selection torque of the particular backstop:

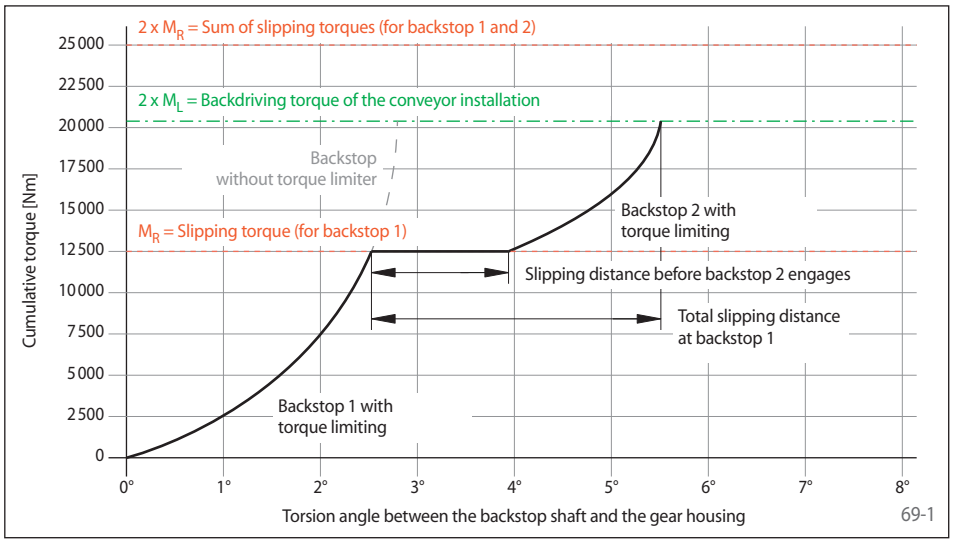
M_A = $1{,}2 \cdot 9550 \cdot 0{,}61 \cdot 630 / 360$ [Nm]

= 12234 Nm

The following rule applies in all cases:

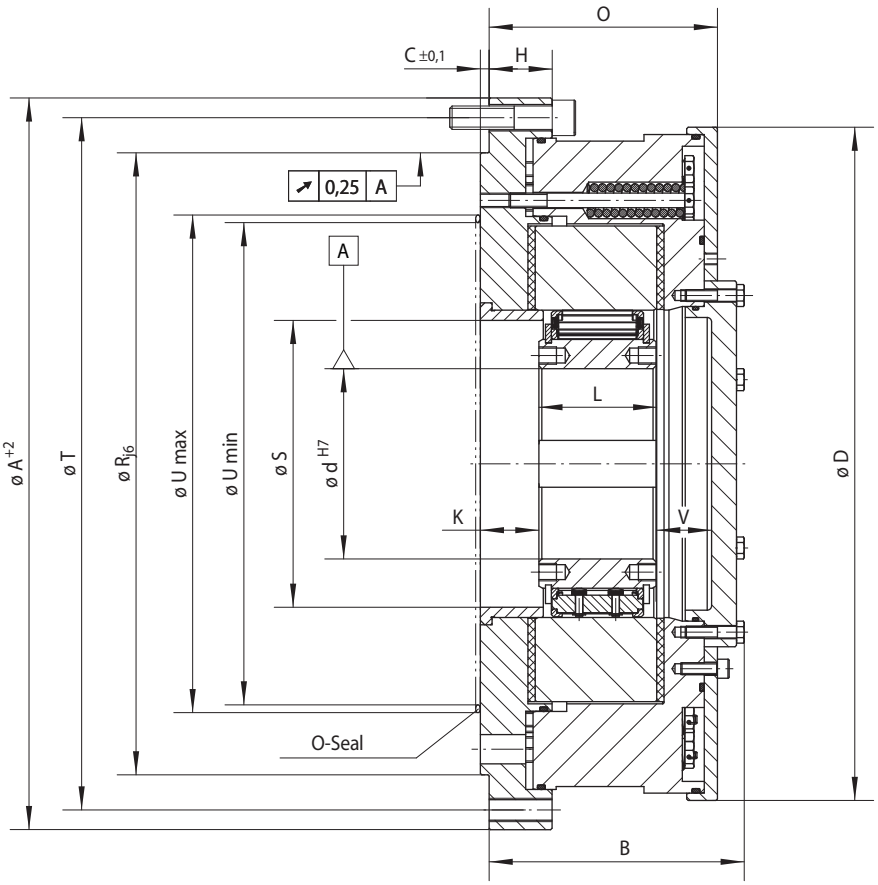
$M_R \geqq M_A$

=> FXRU or FXRW 140 - 63 MX are the suitable, economical backstop sizes.



Integrated Freewheels FXRV

for bolting to the face
with sprag lift-off X and torque limiting



72-1

Backstop

Type with sprag lift-off X For extended service life using sprag lift-off at high speed rotating inner ring	Dimensions

Freewheel Size	Type	Slipping torque M_R Nm	Sprag lift-off at inner ring speed min^{-1}	Max. speed Inner ring freewheels min^{-1}	Bore d Standard mm	Bore d max. mm	A mm	B mm	C mm	D mm	G**	H mm	K mm	L mm	O mm	R mm	S mm	T mm	U*** min. mm	U*** max. mm	V mm	Z**	Weight kg
FXRV 85 - 40	MX	1 400	430	6 000	60	65	330	143	6	295	M 12	37	29	60	127	280	110	308	165	215	43	6	57
FXRV 100 - 50	MX	2 300	400	4 500	70	80*	350	150	6	311	M 12	39	31	70	134	300	125	328	180	240	38	6	65
FXRV 120 - 50	MX	3 400	320	4 000	80	95	400	150	6	360	M 16	36	31	70	134	340	145	373	200	260	38	6	86
FXRV 140 - 50	MX	4 500	320	3 000	90	110	430	160	6	386	M 16	36	31	70	134	375	165	403	220	280	50	6	102
FXRV 170 - 63	MX	9 000	250	2 700	100	130	500	175	6	460	M 16	43	40	80	156	425	196	473	250	340	38	6	163
FXRV 200 - 63	MX	12 500	240	2 100	110	155	555	175	6	516	M 16	49	40	80	156	495	226	528	275	390	38	6	205
FXRV 240 - 63	LX	21 200	220	3 000		185	710	195	8	630	M 20	50	50	90	170	630	290	670	355	455	45	12	347
FXRV 260 - 63	LX	30 000	210	2 500		205	750	205	8	670	M 20	50	50	105	183	670	310	710	375	500	40	12	411
FXRV 290 - 70	LX	42 500	200	2 500		230	850	218	8	755	M 24	52	50	105	190	730	335	800	405	560	48	12	562
FXRV 310 - 96	LX	53 000	195	2 100		240	900	260	10	800	M 24	63	63	120	240	775	355	850	435	600	69	12	792
FXRV 360 - 100	LX	75 000	180	1 800		280	975	267	10	870	M 30	63	63	125	243	850	400	925	485	670	71	12	942
FXRV 410 - 100	LX	100 000	170	1 500		300	1 060	267	10	950	M 30	63	63	125	243	950	450	1 000	535	750	71	12	1 053

Keyway according to DIN 6885, page 1 • Tolerance of keyway width JS10. * Keyway according to DIN 6885, page 3 • Tolerance of keyway width JS10.
** Z = Number of fastening holes for screws G (DIN EN ISO 4762) on pitch circle T. *** Area for O-ring sealing.
See page 69 for determination of selection torque. Other freewheel sizes upon request.

Torques

The Integrated Freewheels FXRV are supplied with a set slipping torque M_R of the torque limiter. The static backdriving torque M_L of the installation (also in the case of an overload) must under no circumstances achieve the sum of the slipping torques M_R of the provided Integrated Freewheels. The slipping torques M_R specified in the table are maximum values; lower values can be set.

Mounting

The Integrated Freewheels FXRV are without bearing support, therefore it must be ensured that the run out (T.I.R.) between the pilot diameter R and the shaft diameter d does not exceed the value 0,25 mm.

Dimension C applies for the Integrated Freewheel. The centering depth of the customer attachment part must be at least C +0,2 mm. The tolerance of the pilot diameter R of the attachment part must be ISO H7.

The tolerance of the shaft must be ISO h6 or j6.

Example for ordering

Freewheel size FXRV 170-63 MX, type with sprag lift-off X, 100 mm bore and slipping torque 9 000 Nm:

- FXRV 170 - 63 MX, d = 100 mm, M_R = 9 000 Nm